

# Tutorial 2: Python Scripts

Dr. Heather L. Kline National Institute of Aerospace August 9<sup>th</sup>, 2019



### Agenda

- Get the tutorial files
- Start the simulation (generate a drag polar)
- Introduction to python scripts distributed with SU2
  - Drag polar
  - Shape optimization
- Anatomy of a python script
- Results of the simulation

#### Acknowledgments

The files for this tutorial are based on a test case for the compute\_polar.py script developed by E. Arad

NATIONAL INSTITUTE OF AEROSPACE



## **Tutorial Files And Required Settings**

- Set PYTHONPATH (if not already done): export SU2\_RUN=<..../bin/> (path to SU2\_CFD, etc) export PYTHONPATH=\$PYTHONPATH:\$SU2\_RUN
  - Python scripts require the path in order to find all the functions that are defined in subfolders.
  - Python scripts can now be called from any folder without moving the scripts.
- Get and extract configuration, mesh and solution files:
- Move to the new directory: cd WorkshopTutorial2/
  - Similar to files needed for SU2\_CFD analysis.
  - Additional 'ctrl' file for polar computation definition
- The files for this tutorial are based on a test case for the compute\_polar.py script developed by E. Arad.
- Modify to use paraview if needed.



### Starting the Simulation

#### compute\_polar.py -c polarCtrl.in -n 2 -i 1000 >& out.txt &

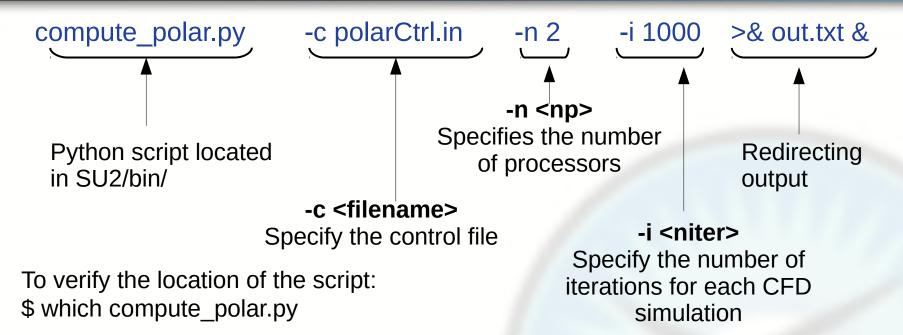
To verify the location of the script: \$ which compute\_polar.py

To check the number of available processors: \$ nproc

To follow the output to opt.out: \$ tail -f out.txt



### Starting the Simulation



To check the number of available processors: \$ nproc

To follow the output to opt.out: \$ tail -f out.txt

NATIONAL INSTITUTE OF AEROSPACE



## More about compute\_polar.py

- compute\_polar.py -h
- PolarCtrl.in file
- open compute\_polar.py in a text editor

**compute\_polar.py -h** Usage: compute\_polar.py [options]

Options:

```
 -h, --help show this help message and exit
 -c FILE, --ctrl=FILE reads polar control parameters from FILE (default:polarCtrl.in)
 -n PARTITIONS, --partitions=PARTITIONS number of PARTITIONS
 -i ITERATIONS, --iterations=ITERATIONS number of ITERATIONS
 -d geomDim, --dimmension=geomDim Geometry dimension (2 or 3)
 -w, --Wind Wind system (default is body system
 -v, --Verbose Verbose printout (if activated)
```

NATIONAL INSTITUTE OF AEROSPACE



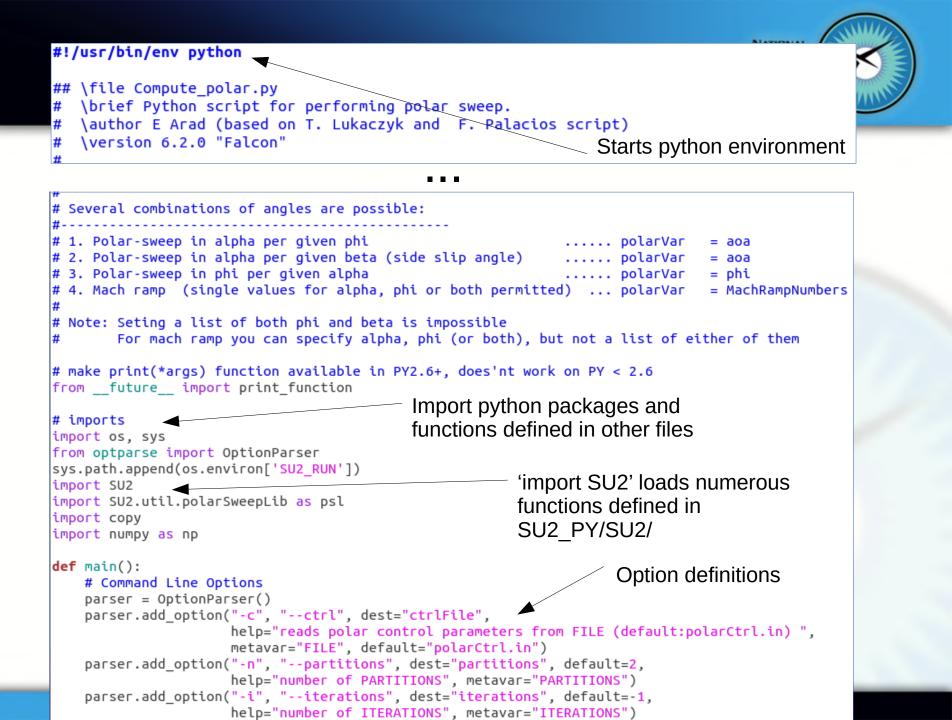
#### **Python Scripts**

- Source code location: SU2/SU2\_PY/
- Installed location: SU2/bin/
- To run a local version: ./python\_script.py
- To run version installed in the bin/ directory: python\_script.py

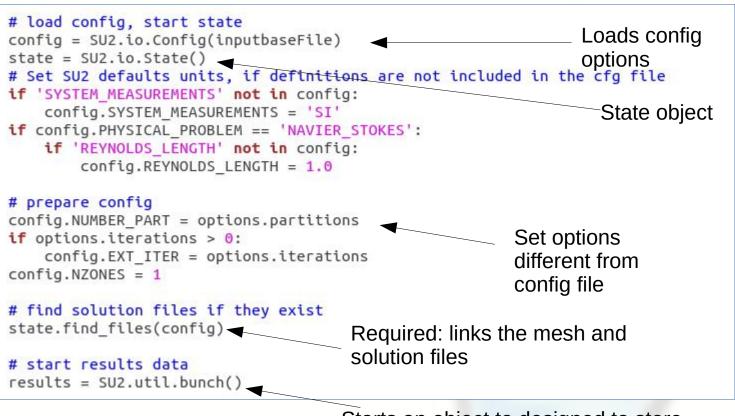
#### 🔻 💕 SU2

autom4te.cache

- 🕨 🚌 Common
- 🕨 🚌 externals
- ▶ 🗁 m4
- 🕨 🗁 QuickStart
- SU2\_CFD
- SU2\_DEF
- SU2\_DOT
- SU2\_GEO
- SU2\_IDE
- SU2\_MSH
- SU2\_PY
- Esi
  pySU2
- E SU2
- eval
- 🕨 🗁 io
- 🕨 🗁 mesh
- 🕨 🗁 opt
- 🕨 🗁 run
- 🕨 🗁 util
- \_\_init\_\_.py
- change\_version\_number.py
- change\_version\_number.py~
- compute\_polar.py
- compute\_stability.py
- config\_gui.py
- continuous\_adjoint.py
- direct\_differentiation.py
- discrete\_adjoint.py



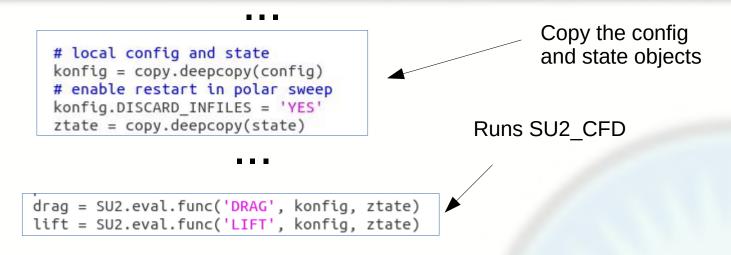




. . .

Starts an object to designed to store solutions





The state object stores whether the solution has already been run:

- Only the first SU2.eval.func... will start a new simulation, subsequent calls will pull from stored data.

- A deepcopy is necessary to avoid pulling results from previous solutions.



Runs function defined in 'main' when script is executed at the command line



#### The Other Python Scripts

- parallel\_computation.py
  - Most used: runs a parallel SU2\_CFD simulation using a specified input file and number of processors.
  - MPI behavior defined in SU2/run/interface.py
- finite\_differences.py, continuous\_adjoint.py, discrete\_adjoint.py
  - Evaluate gradients using the associated method.
  - Uses the design variables and deformation settings defined in the SU2 config file.
- set\_ffd\_design\_var.py
  - Generates FFD box design variable definitions
- shape\_optimization.py
  - Executes a shape optimization problem defined in a specified SU2 config file, using gradient information with a method specified by script inputs.
  - More on this covered in a later tutorial in this workshop.
  - Next: what is optimization?

### Introduction to Optimization



Specifications Baseline Evaluate  $J(\vec{x}) \& c(\vec{x})$ Change Design Deform Geometry Evaluate  $\frac{\partial J}{\partial \vec{x}}$  &  $\frac{\partial c}{\partial \vec{x}}$ Pick search direction **Optimized?** no yes **Fixed** Design

Non-Linear Program:

minimize with respect to  $\vec{x} \in \mathbb{R}^n$ 

 $J(\vec{x})$ subject to  $\hat{c}_i(\vec{x}) = 0, \quad j = 1, ..., \hat{m}$  $c_k(\vec{x}) \geq 0, \quad k = 1, ..., m$ 

 $\vec{X}$  : design variables, bump functions, FFD control points

J: objective function, an evaluation of SU2 CFD

c : constraints, an evalution of SU2 CFD or SU2 GEO

Optimization Algorithm: SciPy SLSQP Gradient Techniques: continuous adjoint, finite difference, discrete adjoint.



### Results from compute\_polar.py script

- Polar\_M0.8.dat
  - Output of AoA, Mach, and aerodynamic coefficients
- DIRECT\_... folders



### Questions?

### Up next: hackathon